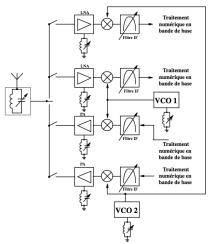
MEMS RF: a review

Master SESI,
UE MEMS,
Cours 3
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Outline

- Introduction
- MEMS RF switches
- Liquid Metal RF switches
- MEMS Resonators

Application domain: the SoftWare Defined Radio



RF application trend : multistndard transievers

Frequency definig components: filters, oscillators

Way to achieve reconfigurability:

- frequency tunning
- switching

MEMS technology is promising for the both.

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Application domain: the SoftWare Defined Radio

Hisory

MEMS metal-to-metal DC-60 GHz switch: Rockwell Science Center, 1995

MEMS Capacitive 10-120 GHz switch: Texas Instruments, 1995

1998 : research in MEMS RF area is very active in american academic laboratories (Berkeley, UCLA, Michigan, MIT...)

2001 : more that 30 companies working in the area, including Motorola, AD, Samsung, STM, \dots

Application domain: the SoftWare Defined Radio

Four distinct areas :

RF MEMS switches, vacastors and inductors: DC-120 GHz

Micromachined hyperfrequency components: transmission lines, high-Q resonators, filter, antenna (12-200 GHz). No mobile parts, no operation in mechanical domain. Not a truly MEMS devices, but using technologies similar with MEMS devices.

FBAR (thin Film Bulk Acoustic Resonators), filters: integrable very high Q filters/resonators for <3 GHz applications, essentially in wireless communications

Mechanical resonators based RF resonators and filters : promising but still marginal in RF applications

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RF switches : MEMS vs Solidstate

TABLE 1.2. Performance Comparison of FETs, PIN Diode, and RF MEMS Electrostatic Switches

Electrostatic Direction				
Parameter	RF MEMS	PIN	FET	
Voltage (V)	20-80	±3-5	3-5	
Current (mA)	0	3-20	0	
Power consumption ^a (mW)	0.05 - 0.1	5-100	0.05 - 0.1	
Switching time	1-300 μs	1-100 ns	1-100 ns	
C_{up} (series) (fF)	1-6	40-80	70-140	
R_s (series) (Ω)	0.5-2	2-4	4-6	
Capacitance ratio ^b	$40-500^{b}$	10	n/a	
Cutoff frequency (THz)	20-80	1-4	0.5 - 2	
Isolation (1–10 GHz)	Very high	High	Medium	
Isolation (10-40 GHz)	Very high	Medium	Low	
Isolation (60–100 GHz)	High	Medium	None	
Loss (1-100 GHz) (dB)	0.05 - 0.2	0.3-1.2	0.4 - 2.5	
Power handling (W)	<1	<10	<10	
Third-order intercept point (dBm)	+66-80	+27-45	+27-45	

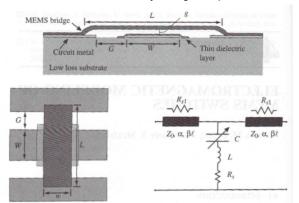
[&]quot;Includes voltage upconverter or drive circuitry.

Capacitive switches

The most efficient and promising, since no mechanical

contact : a large lifetime

Drawbacks: efficient only at high frequencies, limited insulation



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Capacitive switches

Typical parameters :

dielectric thickness 1000-1500 Å Dielectric constant : 5.0-7.6 Bridge height (g) : 1.5-5 μm,

length L : 250-400 μ m, width W : 25-180 mm

mm-wave switches:

capacitance: 35fF/3 pF parasitic inductance 6-12 pH series resistance: 0.2-0.3 Ohms

X-band switches:

Capacitance : 70 fF/5.6 pF, inductance 4-5 pH,

resistance 0.1-0.2 Ohms

Performances:

- The resonance frequency

$$f_0 = \frac{1}{2\pi} \frac{1}{\sqrt{LC}}$$

Cutoff frequency: the frequency where the capacitance ratio of the off (up-state) and on (downstate) degrades to unity:

$$f_c = \frac{1}{2\pi C_u R_s}$$

^bCapacitive switch only. A ratio of 500 is achieved with high- ε_r dielectrics.

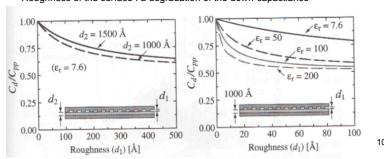
Capacitive switches

- •Up-capacitance : the dielectric layer can be neglected
- •Tens of fF
- •Holes in the upper membrane : needed for the releasing of the mobile part
- •Holes: 4-6 mm diameter, spaced by 5-6 mm period.
- •Typical gap: 3-4 mm
- •The holes don't affect the up-state capacitance: fringe field
- •(D_h<3g: the up capacitance is not affected)

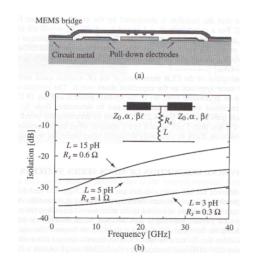
Capacitive switches

- Down capacitance : defined by the dielectric (thickness, dielectric constant).
- Should be as high as possible, however, limited by the Minimal thickness of dielectric (~1000-1500 Å) which should support the actuation voltage (20-50 V)

Roughness of the surface: a degradation of the down-capactiance

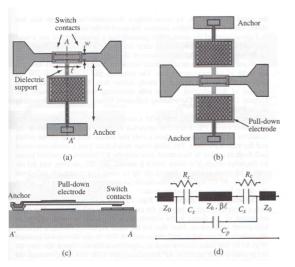


DC-contact shunt switches



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DC-contact series switches



DC-contact series switches

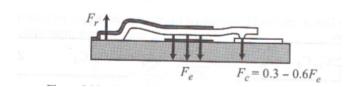
Relevant parameters:

Up-state capacitance Contact series resistance Inductance

Gold-to-gold contact : 0.1 Ohms for applied force of 100-500 μN , contact area of 20 μm^2 ,

MEMS switches contact forces

 The contact force: may be different from the pull-in force

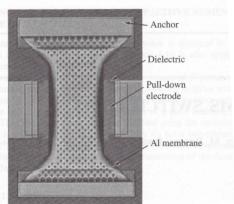


MEMS switches and pull-in phenomenon

- Two parameters: pull-in voltage and hold-down voltage
- Hysteretis characteristic x(V)
- Exercice: calculate the pull-in voltage and the pull-down voltage if W=100μm, w=80 μm, k=30 N/m, t_d=0.1 μm, eps=7. k is supposed to be constant
- · Calculate the contact force in down position

Examples of RF switches

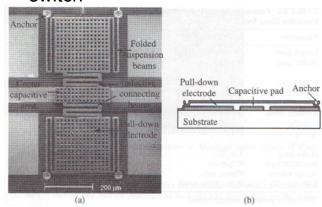
Raytheon capacitive shunt switch



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Examples of RF switches

Univ. Michigan MEMS capacitive shunt switch



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Examples of RF switches

Univ. Michigan MEMS capacitive shunt switch TABLE 5.2. Parameters for the University of Michigan Low-Voltage MEM

Parameter	Value	Parameter	Value	
Length [µm]	500-700	Actuation area [µm²]	200 × 200 (×2)	
Width [µm]	200-250	Actuation voltage ^a [V]	6–20	
Height [µm]	4-5	Switch time ^a [µs]	20-40 (D)	
Membrane type	Nickel	C_d [pF]	1-3	
Thickness [µm]	2-2.5	Capacitive ratio	30-50	
Residual stress [MPa]	20–100	Inductance [pH]	1–2	
Spring constant [N/m]	1–10	Resistance $[\Omega]$	0.2-0.3	
Holes [µm]	Yes (10)	Isolation [dB]	-25 (30 GHz)	
Sacrificial layer	Polyimide	Intermodulation	N/A	
Bridge release Dielectric (Å)	Plasma etch Si ₃ N ₄ (1000–1500)	Loss [dB]	-0.1 (1-40 GHz	

Liquid Metal MEMS switch

- · Drawback of the ohmic switches:
 - Lifetime: up to 100 billions of cycles, however, doubts exist about their long-term reliability
 - Two common failure mecanism :
 - Dielectric charging
 - Contact degradation
 - · Causes: arcing, welding at the solld-solid contact
 - One of the solutions : contact based on liquid metal

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Liquid Metal MEMS switch

- Idea of LM swich: the contact electrodes are coated with a liquid metal layer (mercury, gallium, galinstan...), or the contact is achieved with a droplet of liquid metal
- The contact quality is better (no bouncing), the solid contact supports are less damaged
- The switch lifetime is much greater

Liquid Metal MEMS switch

Liquid metals:

- There is only 5 chemical elements liquid at the ambiant temperature: Mercury, Gallium, Cesium, Francium and Bromine
- Three materials used in switches: mercury, gallium and gallistan (a gallium-based alloy)

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Liquid Metal MEMS switch

Mercury:

- Hg, discovered around 500 B.C.
- Melting point :-38,84°C, a fair (not excellent) thermal and electrical conductor
- Boils at 357°
- The surface tension: 485 mN/M at room temperature
- Very toxic, use highly restricted over past decades

Liquid Metal MEMS switch

Gallium:

- Ga, Discovered in 1875 by Lecoq de Boisbaudran (Gallium <=Gallus=Lecoq).
- Melting point :29,77 °C
- Boils at 2205°C
- The highes surface tension : 680 mN/M at melting point
- Very agressive (attack nearly every metals)

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Liquid Metal MEMS switch

Galinstan:

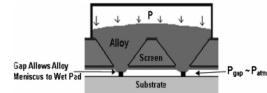
- 68.5% gallium, 21.5% indium, 10% tin,
- The name: Gal + In + Stan (stannum = lat. of tin)
- Widely used for mercuryless thermometers
- Nontoxic
- Very promising material for swithes
- Good conductor (better thant mercury)
- Melting point : -19°C
- Boiling point: >1300°C
- · Easily wet and adheres to most surfaces
- · Gallium oxide coat : prevents from the wetting

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Liquid Metal MEMS switch

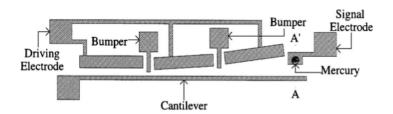
LM deposition: a challenging task

- The goal : to deposit a micrometer-size droplet
- · Complicated because of high surface tension
- · Mercury: slective condensation of mercury vapor on a gold plate
- · Gallium and Gallium Alloys: the lowest vapor pressure among metals
 - Very difficult to evaporate
 - Must be heated to 750°C
 - Screen printing technology (Truong, 2000)



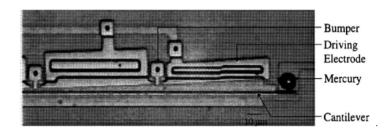
Electrostatically driven microcantilever-based mercury contact (1996)

- Shaped electrodes
- Bumpers prevent the contact with electrodes
- Mercury droplet captured at the contact point



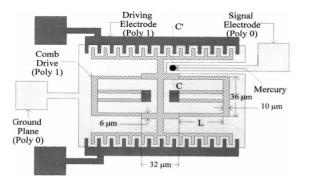
Electrostatically driven microcantilever-based mercury contact (1996)

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Electrostatically driven combdrive-based mercury contact switch (1998)

- Comb-driven electrode,
- Back (bottom) transducer increases the restoring force



Electrostatically driven combdrive-based mercury contact switch (1998)

- Comb-driven electrode,
- Back (bottom) transducer increases the restoring force



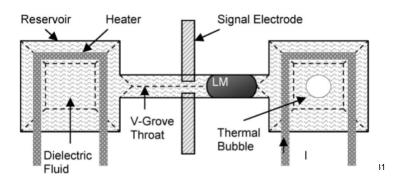
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Electrostatically driven combdrive-based mercury contact switch (1998)

- Actuation voltage: 35 V DC
- 4 μm mobile contact travel
- 4 Hz actuation frequency (?)
- 11 mA max. switching current

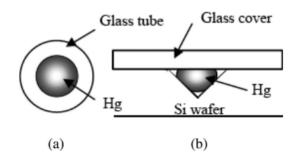
LM-actuaded switches

 The earliest LM-actuated switch (Simon et al., 1996): thermal vapor buble actuated LM microrelay



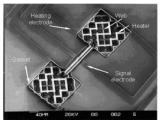
LM-actuaded switches

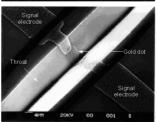
- The earliest LM-actuated switch (Simon et al., 1996) : thermal vapor buble actuated LM microrelay
- Possible canal profiles



LM-actuaded switches

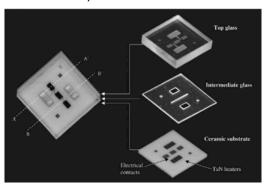
- The earliest LM-actuated switch (Simon et al., 1996): thermal vapor buble actuated LM microrelay
- · Photo of the fabricated device





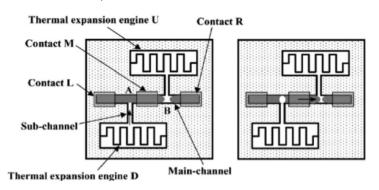
LM-actuaded switches

• Thermally actuated LM (2000, Kondoh et al.)



LM-actuaded switches

 Thermally actuated LM (2000, Kondoh et al.)



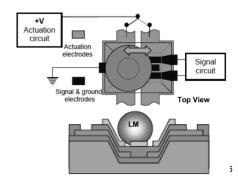
LM-actuaded switches

· Electrostatically actuated LM droplet: 2002, Kim et al.

Actuating force: 6.7 μN for a 300 μm diameter droplet

Actuation voltage: 100-150 V DC

Frequency: 1 Hz



LM-actuaded switches

 Electrostatically actuated LM droplet: planar design by Shen

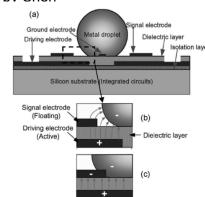
et al., 2006

Actuation voltage: 15V

Stability issue : only 3g

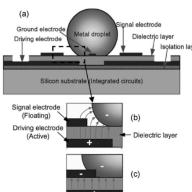
stability

With 80 V DC actuation voltage, 300g stability



LM based MEMS switches

- Promising field, but many material issues,
- The state of developme embrionic
- Further R&D are require _
- A key technology: a low temperature hermetic p in indert environment



RF MEMS resonators

Main applications : oscillators and filters

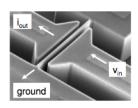
Filters: BAW resonators/filters (Bulk Acoustic Wave) Oscillators: integrated frequency reference generator

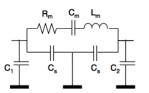
Electrical vs mechanical oscillators (2012)

Resonator	Accuracy	Noise	Size	System integration
technology	df/f ₀ (ppm)	FoM ₂	LxWxH(mm)	
mechanical	<10	~130	>1.6x1.2x0.35	Bulky hermetic package Non-CMOS compatible
electrical	>100	~90	<0.5x0.5X0	•Standard plastic package •CMOS design

RF MEMS resonators

A typical HF clamped-clamped beam resonator geometry

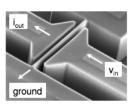


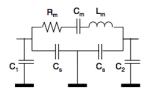


Travaux de Clark T.-C. Nguyen (Berkley) http://www.eecs.berkeley.edu/~ctnguyen

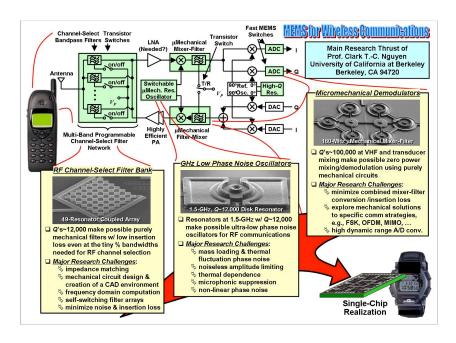
RF MEMS resonators

A typical HF clamped-clamped beam resonator geometry



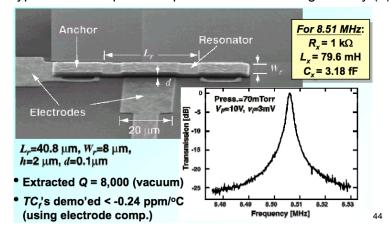


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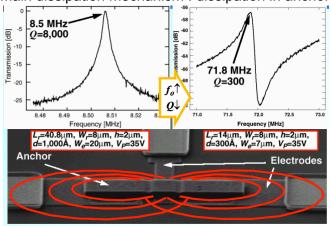


RF MEMS resonators

A typical HF clamped-clamped beam resonator geometry (2)

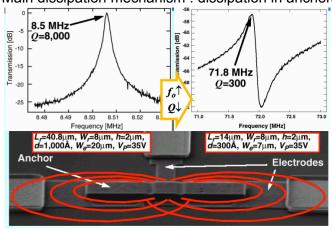


Main dissipation mechanism: dissipation in anchors



RF MEMS resonators

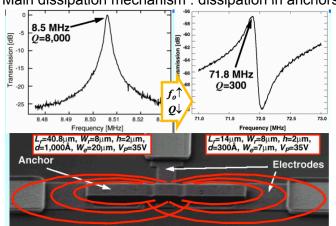
Main dissipation mechanism: dissipation in anchors



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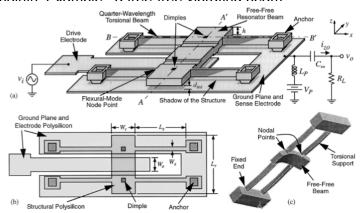
RF MEMS resonators

Main dissipation mechanism: dissipation in anchors



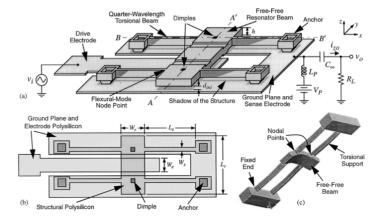
RF MEMS resonators

The solution : clamp the vibrating structure in the fixed vibration points. Example : a free-free vibrating beam



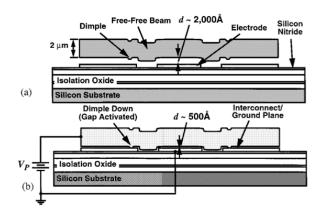
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The solution : clamp the vibrating structure in the fixed vibration points. Example : a free-free vibrating beam (K. Wang et al., 2000)



RF MEMS resonators

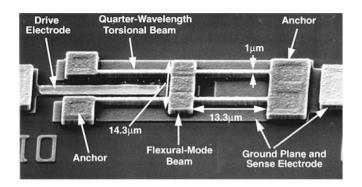
Post fabrication gap reduction (K. Wang et al., 2000)



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RF MEMS resonators

The solution : clamp the vibrating structure in the fixed vibration points. Example : a free-free vibrating beam (K. Wang et al., 2000)

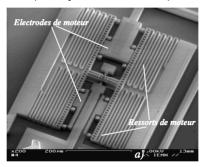


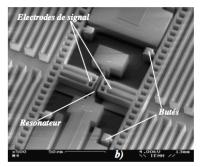
RF MEMS resonators

Parameters of the fabricated free-free beam resonators

	Row	Dosamatas	Source	Target Frequency				Unit
	No.	Parameter	Source	30 MHz	50 MHz	70 MHz	90 MHz	Unit
Designed/Fabricated/Given	1	Resonator Beam Length, L_r	layout	23.2	17.8	14.9	13.1	μm
	2	Resonator Beam Width, Wr	layout	10	10	6	6	μm
	3	Supporting Beam Length, L_s	layout	30.6	18.4	13.1	10.3	μm
	4	Supporting Beam Width, W_s	layout	1	1	1	1	μm
	5	Node Location 1, L_{n1}	layout	5.2	4	3.3	2.9	μm
ed/c	6	Node Location 2, L_{n2}	layout	18	13.8	11.6	10.2	μm
icat	7	Polysilicon Film Thickness, h	measured	2.05	2.05	2.05	2.05	μm
abr	8	Electrode Width, We	layout	7.4	4.5	4	2.8	μm
ed.	9	Typical Initial Physical Gap, dini	measured	1,600	1,600	1,600	1,600	Å
ig	10	Typical Physical Dimple Height, d	measured	1,230	1,230	1,230	1,230	Å
Des	11	Torsion Constant, γ	Eq. (18)	0.469	0.469	0.469	0.469	μm ⁴
	12	Young's Modulus, E	measured	150	150	150	150	GPa
	13	Poisson Ratio, v	[19]	0.226	0.226	0.226	0.226	_
	14	Freq. Modification Factor, ζ	chosen	1	1	1	1	_
=	15	Measured Frequency, fo	measured	31.51	50.35	71.49	92.25	MHz
nrec	16	Measured Quality Factor, Q	measured	8,140	8,430	8,250	7,450	_
Measured	17	V_P Used in Measurement, V_{Pm}	measured	22	86	126	76	V
Σ	18	Measured Series Resistance, R_z	meas./Eq. (24)	31.1	10.7	34.9	167.0	kΩ
	19	Timoshenko Freq., $f_o(V_p=V_{Pm})$	Eq. (9), (5)	30.63	50.83	71.39	90.99	MHz
_	20	Timoshenko Freq., $f_o(V_p=0V)$	Eq. (5)	30.70	51.16	71.64	91.07	MHz
inec	21	Euler-Bernoulli Freq., $f_o(V_P=V_{Pm})$	Eq. (9), (1)	31.62	53.51	76.57	99.29	MHz
em	22	Euler-Bernoulli Freq., $f_o(V_P=0V)$	Eq. (1)	31.68	53.82	76.81	99.36	MHz
Det	23	Calculated Series Resistance, Rz	Eq. (19)	30.9	10.8	34.8	168.9	kΩ
Analytically Determined	24	Adjusted/Extrapolated Gap, d	Eq. (19)	1,300	1,510	1,920	1,780	Å
	25	Resonator Stiffness, $k_r(y=L_r/2)$	Eq. (13)	27,423	57,926	57,390	81,965	N/m
naly	26	Resonator Mass, $m_r(y=L_r/2)$	Eq. (12)	7.40×10 ⁻¹³	5.68×10 ⁻¹³	2.85×10 ⁻¹³	2.51×10 ⁻¹³	kg
¥	27	Dimple-Down Voltage, V _d	Eq. (21)	9.2	25.3	57.4	98.2	V
	28	Catastrophic Pull-In Voltage, V _c	Eq. (11) = 1	232	521	1024	1262	V

10 MHz resonators with post-fabrication gap adjustment (Galayko et al., 2002)

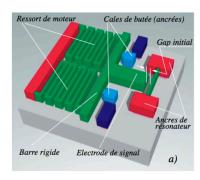


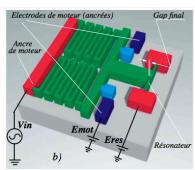


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RF MEMS resonators

10 MHz resonators with post-fabrication gap adjustment (Galayko et al., 2002)

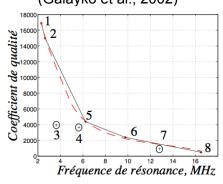




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RF MEMS resonators

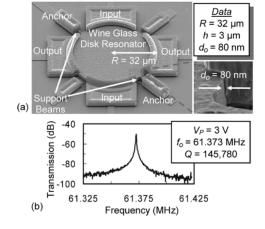
10 MHz resonators with post-fabrication gap adjustment (Galayko et al., 2002)



Dimensions : W=1.8 ⋈m, L=25...100 ⋈m h=15 ⋈m

Very high frequency MEMS resonators: the volume / acoustic waves

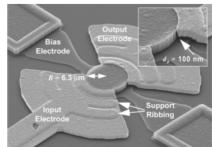
Y. W. Lin et al., 2004



RF MEMS resonators

Very high frequency MEMS resonators: the volume / acoustic waves

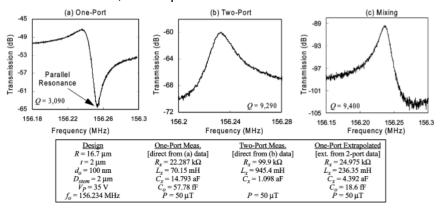
J. R. Clark et al., 2005



RF MEMS resonators

Very high frequency MEMS resonators: the volume / acoustic waves

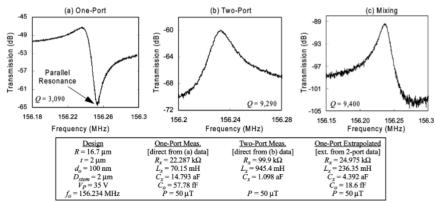
J. R. Clark et al., 2005 : performances



RF MEMS resonators

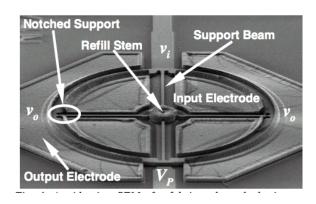
Very high frequency MEMS resonators: the volume / acoustic waves

J. R. Clark et al., 2005 : performances



Very high frequency MEMS resonators: the volume / acoustic waves

S. S. Li et al., 2004:

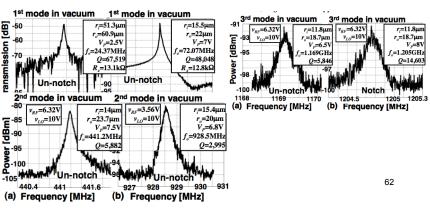


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RF MEMS resonators

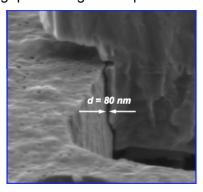
Very high frequency MEMS resonators: the volume / acoustic waves

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RF MEMS resonators

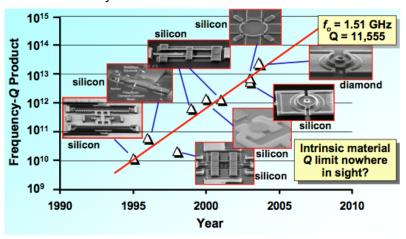
Importance of gap: the impedance at resonance is proportional to gap⁴
Special gap reducing techniques are emploied



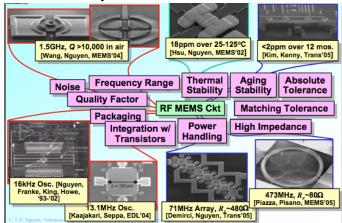
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RF MEMS resonators

Summary of MEMS resonator evolution



Summary of MEMS resonator evolution



Association of MEMS resonators : high order

RF MEMS resonators

analog MEMS filters

Poor drive power capability and high series resistance!

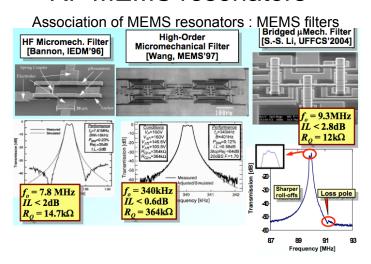
Low frequency

Can't compete with digital signal processing techniques (digital filters)

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RF MEMS resonators

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Another RF MEMS components

Micromachined passive elements: inductors, microstrips

Phase shifters

Variable capacitors

Litterature

- (RF Switches) Gabriel M. Rebeiz, RF MEMS: Theory Design and Technology, Wiley, 2003
- (MEMS resonators)J. T. M. van Beek et al., A review of MEMS oscillators for frequency reference and timing applications, Journal of Micromechanics and Microengineering, 2012, 22, 013001
- (Liquid RF switches) P. Sen et al., Mircoscale Liquid-Metal Switches - A Review, IEEE Transaction on Industrial Electronics, vol. 56, no. 4, april 2009
- (Mems resonators) Clark T.-C. Nguyen group publications: http://www.eecs.berkeley.edu/~ctnguyen
- (MEMS resonators) PhD dissertation of D. Galayko , 2002